MetaGrad Multiple Learning Rates in Online Learning



http://bitbucket.org/wmkoolen/metagrad

Tim van Erven

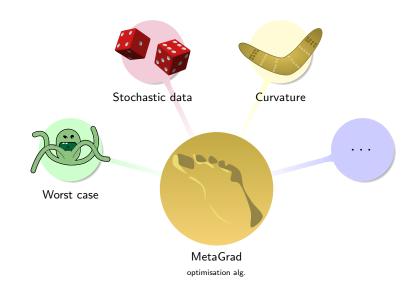


Wouter M. Koolen



NIPS, Barcelona Tuesday 6th December, 2016

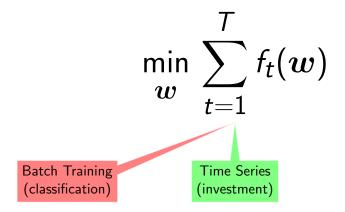
In a Nutshell

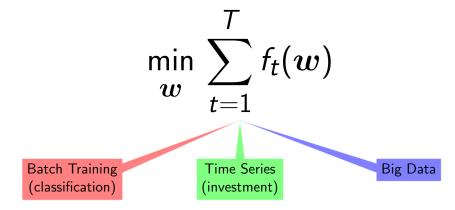


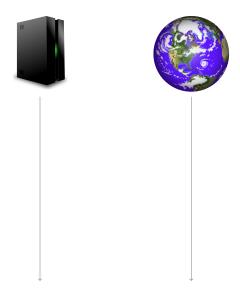
$$\min_{\boldsymbol{w}} \sum_{t=1}^{\prime} f_t(\boldsymbol{w})$$

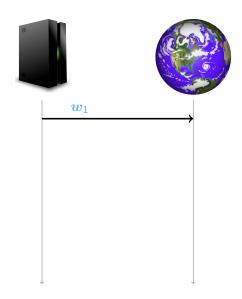
$$\min_{\boldsymbol{w}} \sum_{t=1}^{I} f_t(\boldsymbol{w})$$

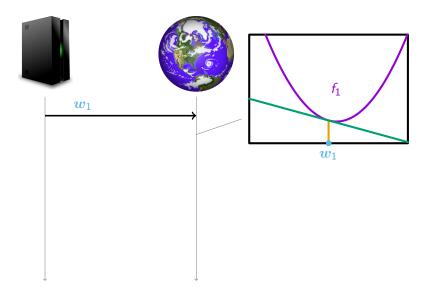
Batch Training (classification)

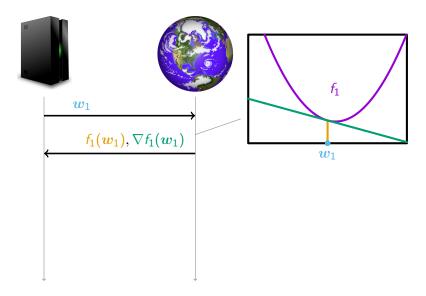


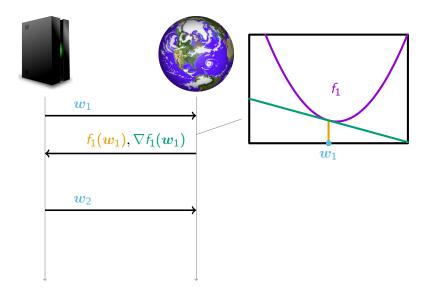


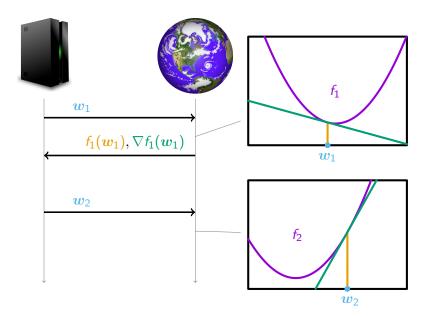


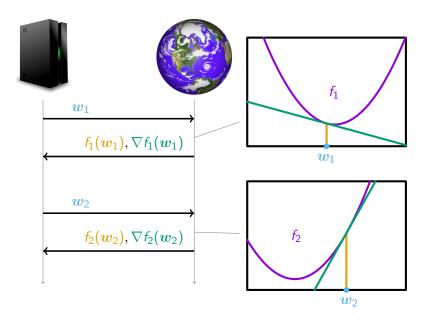


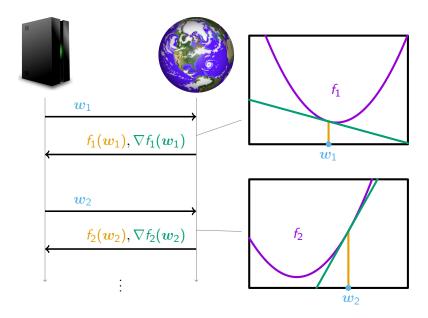




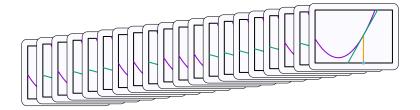








Objective



Definition (Regret)

$$R_T = \underbrace{\sum_{t=1}^{T} f_t(w_t)}_{\text{Online loss}} - \underbrace{\min_{u} \sum_{t=1}^{T} f_t(u)}_{\text{Optimal loss}}$$

Online Gradient Descent [Zinkevich, 2003]

$$|\boldsymbol{w}_{t+1}| = |\boldsymbol{w}_t - \boldsymbol{\eta}_t \nabla f_t(\boldsymbol{w}_t)|$$

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Worst-case regret guarantee:

$$R_T = O\left(\sqrt{T}\right)$$

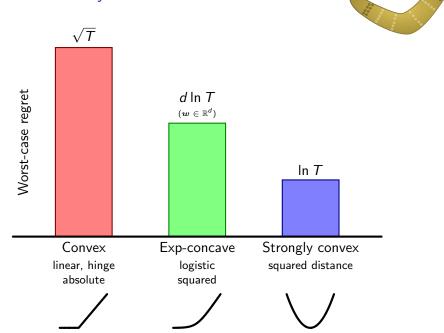
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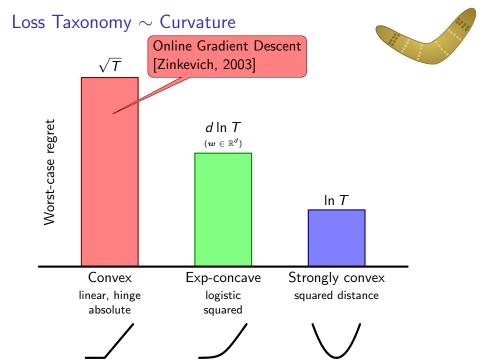
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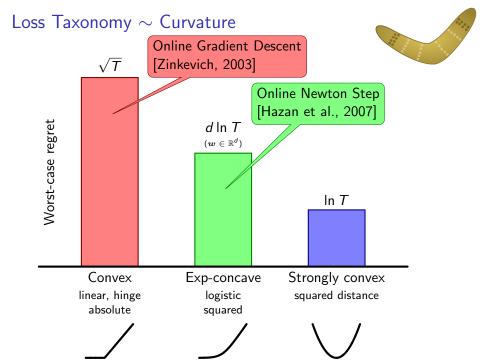
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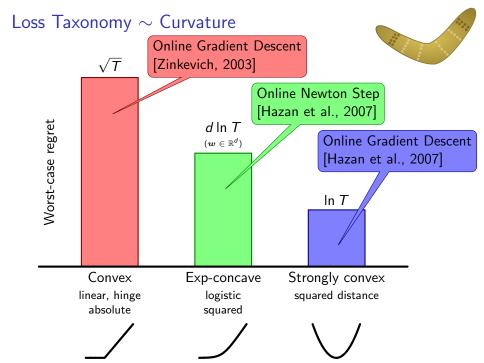
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Loss Taxonomy \sim Curvature









Big Questions

Can we make **adaptive** methods for **online convex optimisation** that are

- worst-case safe
- exploit curvature automatically
- computationally efficient



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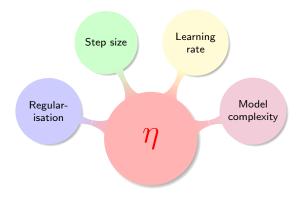
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And can we adapt to other important regimes?

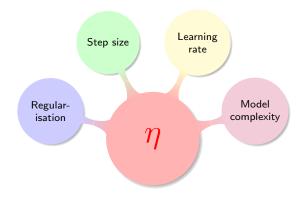
- Mixed or in-between cases?
- Stochastic data? Bandits [Seldin and Slivkins, 2014]
- Absence of curvature? Experts [Koolen and Van Erven, 2015]



For every optimisation algorithm tuning is crucial.

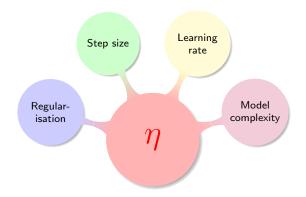


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So let's **learn** optimal tuning from data.

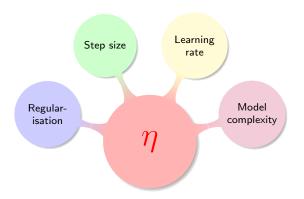
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Key obstacle: avoid learning η at **slow rate** itself.

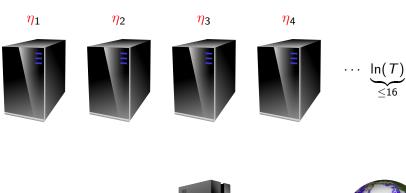
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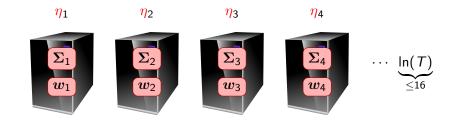
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Breakthrough: Multiple Eta Gradient algorithm (MetaGrad)

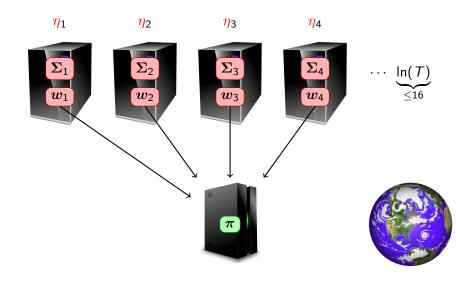


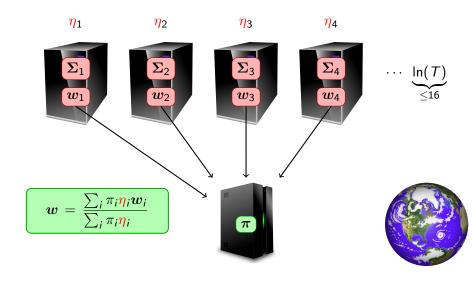


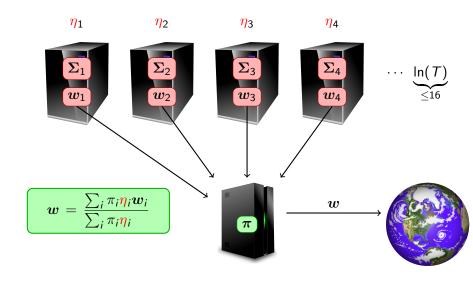


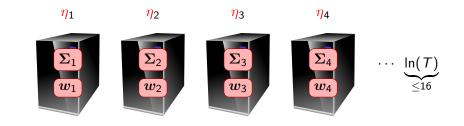




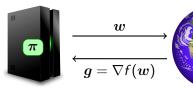


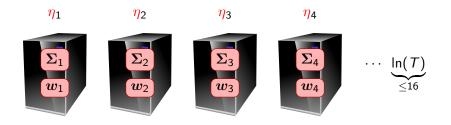




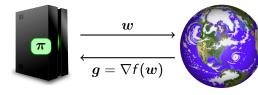


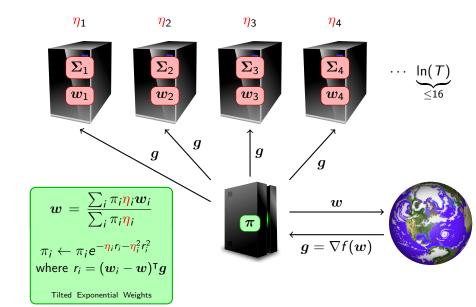
$$w = \frac{\sum_{i} \pi_{i} \eta_{i} w_{i}}{\sum_{i} \pi_{i} \eta_{i}}$$



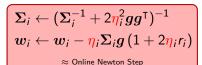


$$m{w} = rac{\sum_i \pi_i m{\eta}_i m{w}_i}{\sum_i \pi_i m{\eta}_i}$$
 $m{\pi}_i \leftarrow m{\pi}_i m{e}^{-m{\eta}_i m{r}_i - m{\eta}_i^2 m{r}_i^2}$ where $m{r}_i = (m{w}_i - m{w})^{\intercal} m{g}$ Tilted Exponential Weights



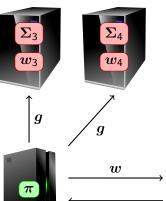


MetaGrad Algorithm



 η_1 η_2 w_1 w_2 $w = \frac{\sum_{i} \pi_{i} \eta_{i} w_{i}}{\sum_{i} \pi_{i} \eta_{i}}$ $\pi_i \leftarrow \pi_i e^{-\frac{\eta_i}{\eta_i} r_i - \frac{\eta_i^2}{\eta_i^2} r_i^2}$ where $r_i = (w_i - w)^{\mathsf{T}} g$

Tilted Exponential Weights



 $q = \nabla f(w)$

 η_3

Second-order Regret Bound



Theorem

The regret of MetaGrad is bounded by

$$R_T = O\left(\min\left\{\sqrt{T}, \sqrt{V_T d \ln T}\right\}\right),$$

where

$$V_{\mathsf{T}} = \sum_{t=1}^{r} ((w_t - u^*)^{\mathsf{T}} \nabla f_t(w_t))^2$$

measures variance compared to the offline optimum $u^* = \arg\min_{u} \sum_{t=1}^{T} f_t(u)$

Note: Optimal tuning depends on unknown optimum u^* .

MetaGrad Adapts to Curvature

MetaGrad regret bound:

$$R_T = O\left(\sqrt{V_T d \ln T}\right)$$



Corollary

For α -exp-concave or α -strongly convex losses, MetaGrad ensures

$$R_T = O(d \ln T)$$

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Reason

Curvature implies $\Omega(V_T)$ cumulative slack between loss and its tangent lower bound.

Consider i.i.d. losses $f_t \sim \mathbb{P}$ with **stochastic optimum**



$$u^* = \arg\min_{u} \mathbb{E} f(u)$$

Goal is small **pseudo-regret** compared to u^* :

$$R_T^* = \sum_{t=1}^T f_t(w_t) - \sum_{t=1}^T f_t(u^*)$$



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For any $\beta ext{-Bernstein }\mathbb{P}$, MetaGrad keeps the expected regret below

$$\mathbb{E} R_T^* \leq O\left((d \ln T)^{\frac{1}{2-\beta}} T^{\frac{1-\beta}{2-\beta}}\right).$$

Fast rates without curvature: e.g. absolute loss, hinge loss, ...



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Reason

Bernstein bounds $\mathbb{E}[V_T^*]$ above by $\mathbb{E}[R_T^*]$. "Solve" regret bound.



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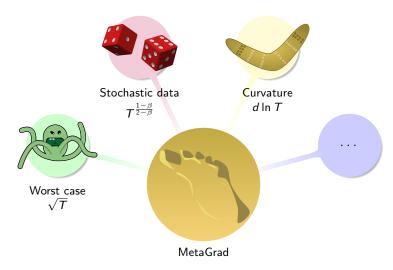
Conclusion

First contact with a new generation of adaptive algorithms.

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MetaGrad adapts to a wide range of environments:



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